## § 25.349

## § 25.345 High lift devices.

(C) \* \* \* \* \* \* \* \*

(2) The vertical gust and turbulence conditions prescribed in §25.341(a) and (b).

\* \* \* \* \*

## §25.349 Rolling conditions.

The airplane must be designed for loads resulting from the rolling conditions specified in paragraphs (a) and (b) of this section. Unbalanced aerodynamic moments about the center of gravity must be reacted in a rational or conservative manner, considering the principal masses furnishing the reacting inertia forces.

- (a) Maneuvering. The following conditions, speeds, and aileron deflections (except as the deflections may be limited by pilot effort) must be considered in combination with an airplane load factor of zero and of two-thirds of the positive maneuvering factor used in design. In determining the required aileron deflections, the torsional flexibility of the wing must be considered in accordance with §25.301(b):
- (1) Conditions corresponding to steady rolling velocities must be investigated. In addition, conditions corresponding to maximum angular acceleration must be investigated for airplanes with engines or other weight concentrations outboard of the fuse-lage. For the angular acceleration conditions, zero rolling velocity may be assumed in the absence of a rational time history investigation of the maneuver.
- (2) At  $V_{A_{i}}$  a sudden deflection of the aileron to the stop is assumed.
- (3) At  $V_C$ , the aileron deflection must be that required to produce a rate of roll not less than that obtained in paragraph (a)(2) of this section.
- (4) At  $V_D$ , the alleron deflection must be that required to produce a rate of roll not less than one-third of that in paragraph (a)(2) of this section.
- (b) Unsymmetrical gusts. The airplane is assumed to be subjected to unsymmetrical vertical gusts in level flight. The resulting limit loads must be determined from either the wing maximum airload derived directly from §25.341(a), or the wing maximum air-

load derived indirectly from the vertical load factor calculated from §25.341(a). It must be assumed that 100 percent of the wing air load acts on one side of the airplane and 80 percent of the wing air load acts on the other side.

[Doc. No. 5066, 29 FR 18291, Dec. 24, 1964, as amended by Amdt. 25–23, 35 FR 5672, Apr. 8, 1970; Amdt. 25–86, 61 FR 5222, Feb. 9, 1996; Amdt. 25–94, 63 FR 8848, Feb. 23, 1998]

## §25.351 Yaw maneuver conditions.

The airplane must be designed for loads resulting from the yaw maneuver conditions specified in paragraphs (a) through (d) of this section at speeds from  $V_{MC}$  to  $V_{D}$ . Unbalanced aerodynamic moments about the center of gravity must be reacted in a rational or conservative manner considering the airplane inertia forces. In computing the tail loads the yawing velocity may be assumed to be zero.

- (a) With the airplane in unaccelerated flight at zero yaw, it is assumed that the cockpit rudder control is suddenly displaced to achieve the resulting rudder deflection, as limited by:
- (1) The control system on control surface stops; or
- (2) A limit pilot force of 300 pounds from  $V_{MC}$  to  $V_A$  and 200 pounds from  $V_{C}/M_C$  to  $V_D/M_D$ , with a linear variation between  $V_A$  and  $V_C/M_C$ .
- (b) With the cockpit rudder control deflected so as always to maintain the maximum rudder deflection available within the limitations specified in paragraph (a) of this section, it is assumed that the airplane yaws to the overswing sideslip angle.
- (c) With the airplane yawed to the static equilibrium sideslip angle, it is assumed that the cockpit rudder control is held so as to achieve the maximum rudder deflection available within the limitations specified in paragraph (a) of this section.
- (d) With the airplane yawed to the static equilibrium sideslip angle of paragraph (e) of this section, it is assumed that the cockpit rudder control is suddenly returned to neutral.

[Amdt. 25-91, 62 FR 40704, July 29, 1997]